

EEE 6109 Wireless Communication.

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Today's Lecture

1. Wideband and directional channel characterization
2. Channel Models
3. Channel Sounding

Introduction

- ▶ The transfer function of the channel varies over the channel bandwidth - frequency selectivity
- ▶ The impulse response of the channel is not a delta function - delay dispersion
- ▶ Wideband channels suffer from intersymbol interference
- ▶ Using appropriate signal processing techniques, the detrimental effects of fading can be overcome

Delay Dispersion

- ▶ Consider the two-path model where the transmit signal gets to the RX via two paths with run times $\tau_1 = d_1/c_0$ and $\tau_2 = d_2/c_0$
- ▶ Let's assume the RX, TX and IOs are stationary. The system is LTI and

$$h(\tau) = a_1\delta(\tau - \tau_1) + a_2\delta(\tau - \tau_2) \quad (1)$$

- ▶ We can show that the transfer function of this channel depends on frequency resulting in frequency selective fading.
- ▶ There are dips in this transfer function at the notch frequencies

See figure 6.1 in Molisch

Delay Dispersion

- ▶ Channels with frequency selective fading also experience phase distortion.
- ▶ Group delay is given by

$$\tau_{Gr} = -\frac{1}{2\pi} \frac{d\phi_H}{df} \quad (2)$$

where $\phi_H = \arg(H(f))$

See figure 6.2 in Molisch

Description of Wireless Channels

- ▶ If the RX, TX and IOs are static, the channel is time invariant with impulse response $h(\tau)$
- ▶ In general the impulse response is time variant $h(t, \tau)$
- ▶ t is absolute time and τ is delay
- ▶ In general we have

$$y(t) = \int_{-\infty}^{\infty} x(t - \tau)h(t, \tau)d\tau \quad (3)$$

- ▶ If the impulse response is shorter than the time over which the channel varies, we can model the channel as an LTI system

Power Delay Profile

- ▶ The PDP measures how much power from a transmitted delta pulse with unit energy arrives at the RX with a delay between $\tau, \tau + d\tau$

- ▶ We have

$$P_h(\tau) = \lim_{T \rightarrow \infty} \frac{1}{2T} \int_{-T}^T |h(t, \tau)|^2 dt \quad (4)$$

- ▶ The PDP is summarized using the zeroth-order moment

$$P_m = \int_{-\infty}^{\infty} P_h(\tau) d\tau \quad (5)$$

Power Delay Profile

- ▶ The mean delay is

$$T_m = \frac{\int_{-\infty}^{\infty} P_h(\tau) \tau d\tau}{P_m} \quad (6)$$

- ▶ The rms delay spread is

$$S_\tau = \sqrt{\frac{\int_{-\infty}^{\infty} P_h(\tau) \tau^2 d\tau}{P_m} - T_m^2} \quad (7)$$

Example 6.1 in Molisch

Channel Models

- ▶ Stored channel models
- ▶ Deterministic channel models
- ▶ Stochastic channel models

Narrowband Models

- ▶ For a narrowband channel we have

$$h(t, \tau) = \alpha(t)\delta(\tau) \quad (8)$$

Path Loss Models

- ▶ Okumura-Hata model

$$PL = A + B \log(d) + C \quad (9)$$

A, B, and C are factors that depend on frequency and antenna height

- ▶ COST 231-Walfish-Ikegami model
- ▶ Motley-Keenan Model - for indoor environments

$$PL = PL_0 + 10n \log(d/d_0) + F_{wall} + F_{floor} \quad (10)$$

Wideband Models - Tapped Delay Line Models

- ▶ The N-tap Rayleigh-fading model

$$h(t, \tau) = \alpha_0 \delta(\tau - \tau_0) + \sum_{i=1}^N c_i(t) \delta(\tau - \tau_i) \quad (11)$$

- ▶ $c_i(t)$ is a zero-mean complex Gaussian random process

Wideband Models - Power Delay Profile

- ▶ The PDP can be approximated by a one-sided exponential function

$$P_h(\tau) = P_{sc}(\tau) = \begin{cases} \exp(-\tau/S_\tau) & \tau \geq 0 \\ 0 & \text{otherwise} \end{cases}$$

- ▶ Typical values of delay spread
 - ▶ Indoor residential building 5-10ns
 - ▶ Microcell 100-500ns
 - ▶ Hilly Terrain: $18\mu_s$

Deterministic Channel Modelling

- ▶ Ray Launching
- ▶ Ray Tracing
- ▶ Geographical databases

Channel Sounding

- ▶ Measurement of the impulse responses of channel
- ▶ The TX sends out a signal $s(t)$ that consists of periodically repeated pulses

$$s(t) = \sum_{i=0}^{N-1} p(t - iT_{rep})$$

- ▶ The impulse response is estimated from the received signal

See figure 8.3 in Molisch

Readings

- ▶ Molisch - Chapter 6, 7, 8, 10